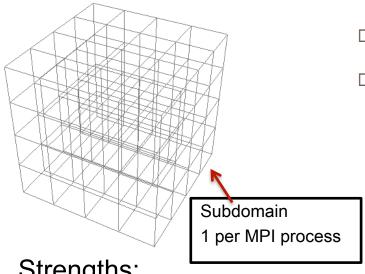
Classic HPC Application Architecture





- Strengths:
 - Portable to many specific system architectures.
 - Separation of parallel model (SPMD) from implementation (e.g., message passing).
 - Domain scientists write sequential code within a parallel SPMD framework.
 - Supports traditional languages (Fortran, C).
 - Many more, well known.

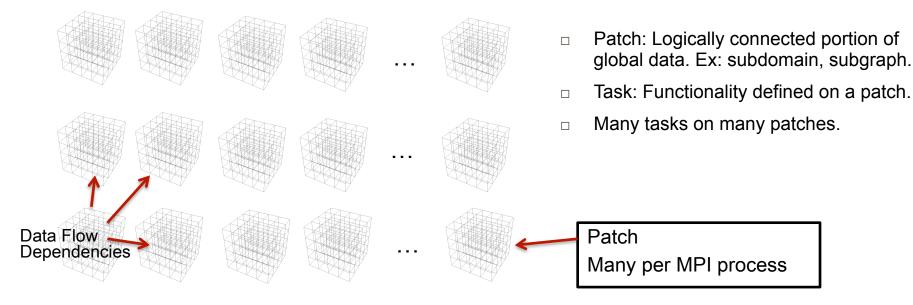
- Logically Bulk-Synchronous, SPMD
- **Basic Attributes:**
 - Halo exchange.
 - Local compute.
 - Global collective.
 - Halo exchange.

Weaknesses:

- Not well suited (as-is) to emerging manycore systems.
- Unable to exploit functional on-chip parallelism.
- Difficult to tolerate dynamic latencies.
- Difficult to support task/compute heterogeneity.

Task-centric/Dataflow Application Architecture





Strengths:

- Portable to many specific system architectures.
- Separation of parallel model from implementation.
- Domain scientists write sequential code within a parallel framework.
- Supports traditional languages (Fortran, C).
- Similar to SPMD in many ways.

More strengths:

- Well suited to emerging manycore systems.
- Can exploit functional on-chip parallelism.
- Can tolerate dynamic latencies.
- Can support task/compute heterogeneity.

Task-centric/Dataflow Application Architecture Characteristics



- Task execution requirements:
 - Tunable work size: Enough to efficiently use a core once scheduled.
 - Vector/SIMT capabilities.
 - Small thread-count SMP.
 - Task data dependencies.
 - Accelerator mode: Big patch.
- Universal portability:
 - Works within node, across nodes.
 - Works across heterogeneous core types.

- Many tasks:
 - Async dispatch: Many in flight.
 - Natural latency hiding.
 - Higher message injection rates.
 - Better load balancing.
- Compatible with "classics":
 - Fortran, C, OpenMP.
 - Used within a task.
- Natural resilience model:
 - Every task has a parent (can regenerate).
- Demonstrated concept:
 - Co-Design centers, PSAAP2, others.

Open Questions for Task-Centric/Dataflow Strategies



- Functional vs. Data decomposition.
 - Over-decomposition of spatial domain:
 - Clearly useful, challenging to implement.
 - Functional decomposition:
 - Easier to implement. Challenging to execute efficiently (temporal locality).
- Dependency specification mechanism.
 - How do apps specify inter-task dependencies?
 - Futures (e.g., C++, HPX), data addresses (Legion), explicit (Uintah).
- Roles & Responsibilities: App vs Libs vs Runtime vs OS.
- Interfaces between layers.
- Huge area of R&D for many years.

Data challenges:

- Read/write functions:
 - Must be task compatible.
 - Thread-safe, non-blocking, etc.
- Versioning:
 - Computation may be executing across multiple logically distinct phases (e.g. timesteps)
 - Example: Data must exist at each grid point and for all active timesteps.
- Global operations:
 - Coordination across task events.
 - Example: Completion of all writes at a time step.

Key messages:

- HPC App architectures are changing, adding further demands and opportunities for big data, big compute co-design efforts.
- Need to know HPC app trends to get combined big data, big compute right.